

Function name: **ZM – Zero monitoring**

Example

The standstill of a machine is to be detected and transferred to marker MS01 as a signal for further processing. A standstill is recognised at a rotation speed of less than 10 rpm. Two inductive proximity switches in conjunction with a cam disk with 12 cams on the shaft measure the speed.

The zero speed monitoring function is always active (ZM01SA = 1).

The rotation frequency to be set on the easySafety is:
 $12 \times 10 \text{ rpm} / 60 = 2 \text{ Hz}$.

This looks as follows in the electrical circuit diagram:

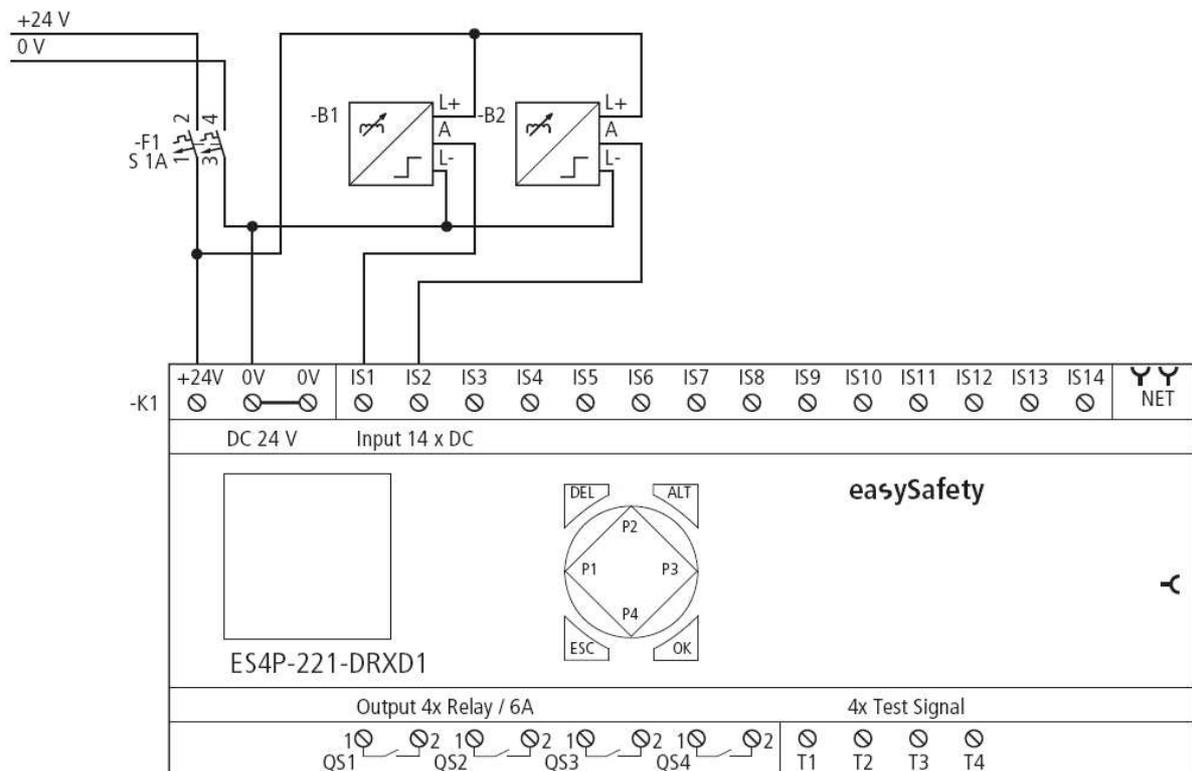


Figure 1: Electrical circuit diagram

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The signal diagram of the function block for this application shows:

- the dependence of the enable contact ZM01QS on the measured frequency at function block coils I:

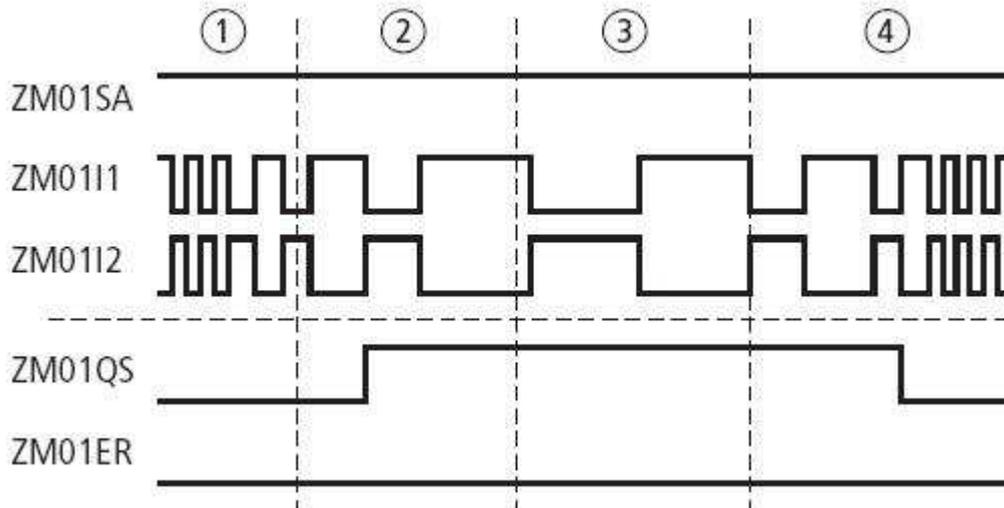


Figure 2: Signal diagram

- 1 The speed is more than 10 rpm, ZM01QS signals: "no standstill".
- 2 The speed is less than 10 rpm, ZM detects the standstill and closes contact ZM01QS.
- 3 The speed of the motor increases and exceeds 10 rpm + 10 % hysteresis (= 11 rpm). ZM01QS opens and thus no zero speed indicated.

Please note: The master-password for the example file is: "111111".