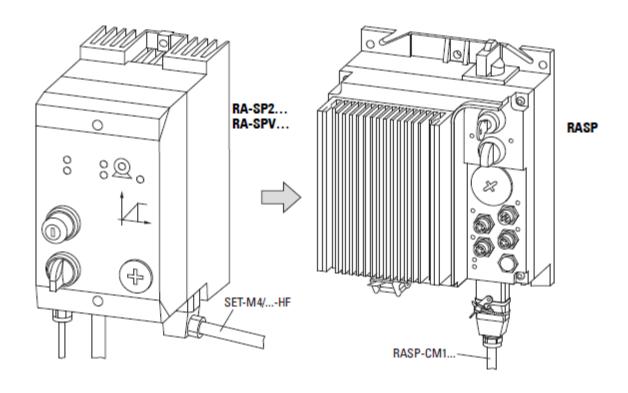
Rapid Link

RASP

Generation Change of RA-SP to RASP 4.0



1 – Fundamental – No previous experience necessary

2 – Basic – Basic knowledge recommended

3 – Advanced – Reasonable knowledge required

4 – Expert – Good experience recommended



Level 3

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Original Application Note is the English version of this document.

All non-English language versions of this document are translations of the original application note.

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Danger! - Dangerous electrical voltage!

- Disconnect the power supply of the device.
- Ensure that devices cannot be accidentally restarted.
- Verify isolation from the supply.
- Cover or enclose any adjacent live components.
- Follow the engineering instructions (AWA/IL) for the device concerned.
- Only suitably qualified personnel in accordance with EN 50110-1/-2 (VDE 0105 Part 100) may work on this
 device/system.
- Before installation and before touching the device ensure that you are free of electrostatic charge.
- The functional earth (FE, PES) must be connected to the protective earth (PE) or the potential equalization. The system installer is responsible for implementing this connection.
- Connecting cables and signal lines should be installed so that inductive or capacitive interference does not impair
 the automatic control functions.
- Suitable safety hardware and software measures should be implemented for the I/O interface so that an open circuit on the signal side does not result in undefined states.
- Deviations of the mains voltage from the rated value must not exceed the tolerance limits given in the specification, otherwise this may cause malfunction and/or dangerous operation.
- Emergency stop devices complying with IEC/EN 60204-1 must be effective in all operating modes. Unlatching
 of the emergency-stop devices must not cause a restart.
- Devices that are designed for mounting in housings or control cabinets must only be operated and controlled after they have been properly installed and with the housing closed.
- Wherever faults may cause injury or material damage, external measures must be implemented to ensure a safe
 operating state in the event of a fault or malfunction (e.g. by means of separate limit switches, mechanical
 interlocks etc.).
- Frequency inverters may have hot surfaces during and immediately after operation.
- Removal of the required covers, improper installation or incorrect operation of motor or frequency inverter may destroy the device and may lead to serious injury or damage.
- The applicable national safety regulations and accident prevention recommendations must be applied to all work carried on live frequency inverters.
- The electrical installation must be carried out in accordance with the relevant electrical regulations (e. g. with regard to cable cross sections, fuses, PE).
- Transport, installation, commissioning and maintenance work must be carried out only by qualified personnel (IEC 60364, HD 384 and national occupational safety regulations).
- Installations containing frequency inverters must be provided with additional monitoring and protective devices
 in accordance with the applicable safety regulations. Modifications to the frequency inverters using the operating
 software are permitted.
- All covers and doors must be kept closed during operation.
- To reduce the hazards for people or equipment, the user must include in the machine design measures that
 restrict the consequences of a malfunction or failure of the frequency inverter (increased motor speed or
 sudden standstill of motor). These measures include: Other independent devices for monitoring safety
 related variables (speed, travel, end positions etc.).
 - Electrical or non-electrical system-wide measures (electrical or mechanical interlocks).
 - Never touch live parts or cable connections of the frequency inverter after it has been disconnected from the power supply. Due to the charge in the capacitors, these parts may still be alive after disconnection. Consider appropriate warning signs.

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1 General

The following information indicates the differences that must be taken into account when expanding systems or creating new projects with RASP (Rapid Link 4.0) units, as well as when using them to replace RA-SP2... and/or RA-SPV... devices.

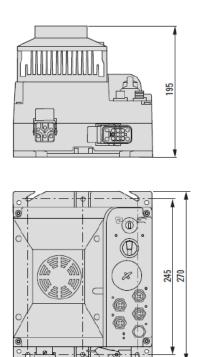
The devices have the following major differences:

- Dimensions
- AS-Interface profile
- Parameter software and technical overview
- Type and design of motor cables.

The controls' handling and functions remain the same. RASP combines the functionality of RA-SP2... and RA-SPV... in a single device. If required, the vector functionality can be activated via the parameters.

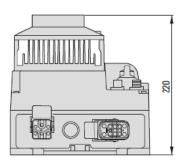
2 Dimensions

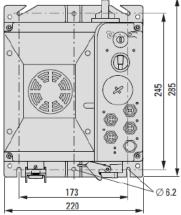
Figure below shows the dimension of new RASP devices:



RASP 2.2 kW with device fan

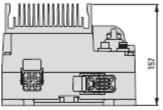
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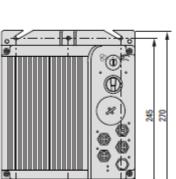




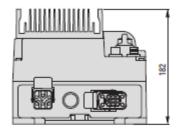
RASP 2.2 kW with device fan with maintenance and repair switch

RASP speed controllers









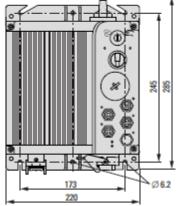


Figure 126:RASP -2, RASP -3, RASP -4 with repair and maintenance switch

3 AS-I Profile

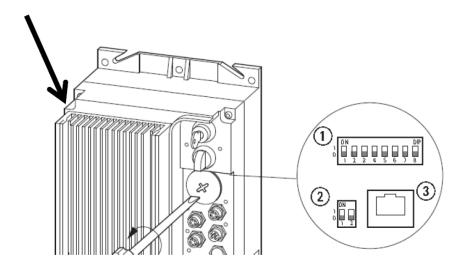
RASP... units have AS-i profile S-7.E.0 (old) and AS-i profile S-7.4 (new). Due to the expanded AS-i profile, the master (gateway) needs to carry out a new initialization process if new RASP devices with profile S-7.4 are used as a replacement. To do this, the AS-i master needs to be switched to configuration mode. In this mode, the AS-i master will recognize the type and profile of the AS-i slaves connected to the AS-i cable. The profile is hardcoded into the slave modules during production and cannot be changed. On e.g. PROFIBUS/AS-i gateways, this configuration mode can usually only be activated if there are no ongoing communications with the PROFIBUS. The assignment of Rapid Link inputs/outputs and the data bits remain the same. The PLC programs do not have to be modified.

4 Replacement Sequence

Proceed following steps for a proper replacement.

- 1. Read the parameter from RA-SP... (with DrivesSoft).
- 2. Read the address from RA-SP... (with Addressing device).
- 3. Note the DIP-Positions of the RA-SP...
- 4. Disconnect Motor-, Energy-, Asi-, Sensor-, Actor connectors from RA-SP...
- 5. Switch Key to HAND Mode (RASP...)
- 6. Set Parameters of the RASP accordingly (with RASP-KEY-S1 or MaxConnect)

- 7. Give the address of RA-SP to the RASP...
- 8. Set the DIP switches of RASP... accordingly.
- 9. Connect all cables, Line 400 V AC, AS-Interface, Motor and Sensors und Actor.
- 10. Ready to start.

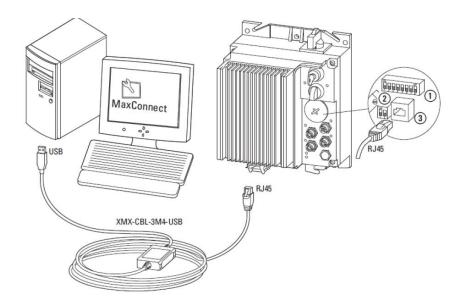




Notice!

Before power on it must be ensured that the motor and the motor cable is properly connected.

5 Communication cable between PC and RASP



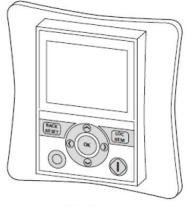
RASP plug for cable screw gland

- 1 Functions, dip switch
- (2) dip switch (currently without function)
- (3) Serial interface (RJ 45)

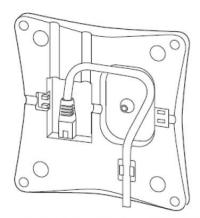
Connection cable XMX-CBL-3M4-USB allows communication and data exchange between RASP and a PC. The cable has a length of about 3.4 m, an interface converter with electrical isolation, an RJ45 plug and a USB port. Connection cable XMX-CBL-3M4-USB is not supplied with the RASP.

6 Optional keypad RASP-KEY-S1

The optional RASP-KEY-S1 keypad enables you to configure the RASP's parameters and view operational data. The Start and Stop keys and the setpoint input have no function. The con-nection to the RASP requires a patch cable with an RJ45 plug. The optional RASP-KEY-S1 LCD keypad is not included with RASP units. The equipment supplied with the RASP-KEY-S1 LCD keypad includes a 1-m long patch cable.



RASP-KEY-S1 (article no.: 156644)

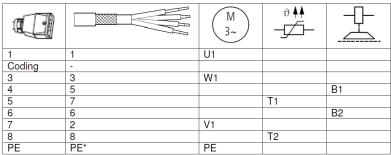


RJ45 socket at the back of LCD keypad RASP-KEY-S1

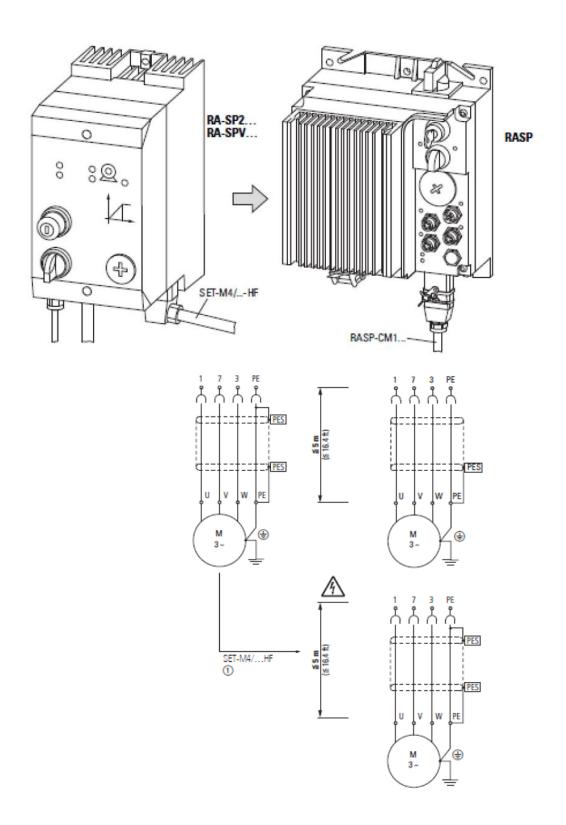
7 RASP Motor cable (RASP-CM1-...)

The motor has to be connected using unshielded, DESINA-compliant, motor cable

RASP-CM1-.. (4 x 1,5mm2 + 2 x (2 x 0.75) mm2) with the following PIN assignment:0



*PE = green-yellow



8 References

Documentation	RASP4.0	RA-SP	LINK
Manual RASP	MN03406003Z-EN	AWA2190-1936	<u>DownloadCenter</u>
Instruction Leaflet RASP 4.0	IL0306020Z	AWB2190-1430E	<u>DownloadCenter</u>

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