

Drives & Soft Starters

List of Application Notes



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Latest Updates:

New Application Note for Rapid Link

➔ Generation Change RA-SP 2 to RASP5

1 General

No	Title / Content	General	9000X	DA1	DC1	DC1...E1	DE1	DG1
AP040043EN	Electromagnetic compatibility (EMC) • EMC compatible setup • EMC from directives' and standards' point of view • When are additional measures required / reasonable • Checklist EMC	X						
AP040114EN	Dual Rating – What exactly does that mean?	X						
AP040169EN	Connecting drives to generator supplies • Technical aspects for a reliable operation	X						

2 9000X

No	Title / Content	General	9000X	DA1	DC1	DC1...E1	DE1	DG1
AP040044EN	Variable Frequency Drives with a common DC bus SPI9000 – Application and selection		X					

3 DA1

No	Title / Content	General	9000X	DA1	DC1	DC1...E1	DE1	DG1
AP040016EN	How does the internal motor protection work? • how the motor protection works • Dependency between current and tripping time • Determination of the recovery time after an overload			X	X	X	X	
AP040018EN	Motor data – Motor Protection – V/f curves for induction motors • Selection of the motor control mode • Adaptation to the connected motor • Slip compensation • Motor protection • Setting the V/f curve • Energy optimization			X				
AP040021EN	Access to Parameter Level 2 and 3 – Parameter Lock – RESET • Access to parameter level 2 and level 3 • how to mask out parameters • how to prevent a parameter value change • how to restore the factory / application specific settings (Default)			X				
AP040022EN	The OP System Bus – Parameterizing – Control • Structure of the hardware • Bus configuration • Handling at parameterization and control			X	X	X	X	
AP040023EN	Equal load sharing with the droop function • description of the droop function • application example			X				
AP040025EN	PID controller • function of the specific parameters • mode of operation • application examples			X				
AP040026EN	Master slave operation • functionality • configuration • application examples			X				
AP040028EN	Vector Control of Induction Motors • Selection of the motor control mode • Adaptation to the connected motor • Speed Control (Open Loop Vector) • Speed Control with Encoder (Close loop Vector) • Torque Control • Trouble Shooting			X				

No	Title / Content	General	9000X	DA1	DC1	DC1...E1	DE1	DG1
AP040030EN	Starting, Stopping and Operation - different possibilities at starting and stopping - respective control commands - setting of the relevant parameters - behaviour in case of fault - measures to prevent unintended trips			X				
AP040031EN	Use of multiple ramps - general functionality - configuration of the device depending on the required number of ramps and the ramp mode			X				
AP040032EN	Hoist applications - general functionality - parameter setting - examples			X				
AP040034EN	I/O Configuration - input and output terminals - I/O extension - Technical data - Assignment of functions to terminals - Configuration of the I/Os			X				
AP040039EN	Dependency of the output current on switching frequency and ambient temperature			X				
AP040040EN	Setpoint Setting - Different ways of set point setting - Handling of the references - User specific configuration possibilities			X				
AP040047EN	Closed Loop Vector Control - Speed control with feedback - Connection - Parameter settings - debugging AP040047EN_DA1 Closed Loop Vector Control			X				
AP040051EN	Operating Permanent Magnet and Brushless DC Motors - Selection of the motor control mode - Adaptation to the connected motor - Optimization of the application - Trouble shooting - Example: PM motor settings			X				

No	Title / Content	General	9000X	DA1	DC1	DC1...E1	DE1	DG1
AP040182EN	Conformal Coating • Benefits from Conformal Coating • Eaton Use • Variation & limitations • Relevant standards & Conclusions 1.			X	X	X	X	
AP040183EN	Low Temperature Applications • Basics • Applications • Self-heat function • Drive configuration • Typical application 2.			X	X	X		
AP040189EN	DX-COM-STICK3_Connection • Connect to a PC • Connect with drivesConnect mobile app • Offline parameter copy • Boot-Sequence and Unlocking			X	X	X	X	
AP040190EN	Update DX-COM-STICK3 • Connect to a PC • Enter Firmware Update Mode • Update			X	X	X	X	

4 DC1

No	Title / Content	General	9000X	DA1	DC1	DC1...E1	DE1	DG1
AP040014EN	Motor data – Motor Protection – V/f curves – Slip Compensation • Adaptation to the connected motor • Slip compensation • Motor protection • Setting the V/f curve • Energy optimization				X			
AP040015EN	Access to Parameter Level 2 – Parameter Lock – Load Default • Access to parameter level 2 • how to prevent a parameter value change • how to restore the factory settings (Default)				X			

No	Title / Content	General	9000X	DA1	DC1	DC1...E1	DE1	DG1
AP040016EN	How does the internal motor protection work? • how the motor protection works • Dependency between current and tripping time • Determination of the recovery time after an overload			X	X	X	X	
AP040022EN	The OP System Bus – Parameterizing – Control • Structure of the hardware • Bus configuration • Handling at parameterization and control			X	X	X	X	
AP040024EN	PI controller • function of the specific parameters • mode of operation • application examples				X			
AP040027EN	Starting, Stopping and Operation • different possibilities at starting and stopping • respective control commands • setting of the relevant parameters • behaviour in case of fault • measures to prevent unintended trips				X			
AP040035EN	I/O Configuration • input and output terminals • I/O extension • Technical data • Assignment of functions to terminals • Configuration of the I/Os				X			
AP040037EN	Operating Single Phase Motors • Specialties of DC1-S.... and their application				X	X		
AP040038EN	Dependency of the output current on switching frequency and ambient temperature				X			
AP040041EN	Set Point Setting • Different ways of set point setting • Handling of the references				X			
AP040182EN	Conformal Coating • Benefits from Conformal Coating • Eaton Use • Variation & limitations • Relevant standards & Conclusions			X	X	X	X	
AP040183EN	Low Temperature Applications • Basics • Applications • Self-heat function • Drive configuration • Typical application			X	X	X		

No	Title / Content	General	9000X	DA1	DC1	DC1...E1	DE1	DG1
AP040189EN	DX-COM-STICK3_Connection • Connect to a PC • Connect with drivesConnect mobile app • Offline parameter copy • Boot-Sequence and Unlocking			X	X	X	X	
AP040190EN	Update DX-COM-STICK3 • Connect to a PC • Enter Firmware Update Mode • Update			X	X	X	X	

5 DC1...E1

No.	Title / Content	General	9000X	DA1	DC1	DC1...E1	DE1	DG1
AP040016EN	How does the internal motor protection work? • how the motor protection works • Dependency between current and tripping time • Determination of the recovery time after an overload			X	X	X	X	
AP040022EN	The OP System Bus – Parameterizing – Control • Structure of the hardware • Bus configuration • Handling at parameterization and control			X	X	X	X	
AP040037EN	Operating Single Phase Motors • Specialties of DC1-S... and their application				X	X		
AP040049EN	Motor data – Motor Protection – V/f curves – Slip Compensation • Adaptation to the connected motor • Slip compensation • Motor protection • Setting the V/f curve • Energy optimization • Preset applications					X		
AP040052EN	Access to Parameter Levels 2 + 3 – Parameter Lock – Load Default • Access to parameter levels 2 and 3 • how to prevent a parameter value change • how to restore the factory settings (Default)					X		
AP040053EN	PI controller • function of the specific parameters • mode of operation • application examples					X		
AP040054EN	Starting, Stopping and Operation • different possibilities at starting and stopping • respective control commands • setting of the relevant parameters • behaviour in case of fault • measures to prevent unintended trips					X		

No.	Title / Content	General	9000X	DA1	DC1	DC1...E1	DE1	DG1
AP040057EN	I/O Configuration - input and output terminals - I/O extension - Technical data - Assignment of functions to terminals - Configuration of the I/Os					X		
AP040059EN	Dependency of the output current on switching frequency and ambient temperature					X		
AP040060EN	Set Point Setting - Different ways of set point setting - Handling of the references					X		
AP040063EN	Operating Permanent Magnet and Brushless DC Motors - Selection of the motor control mode - Adaptation to the connected motor - Optimization of the application - Trouble shooting - Example: PM motor settings					X		
AP040064EN	Fire Mode - Configuration - How does DC1...E1 work in Fire Mode?					X		
AP040182EN	Conformal Coating - Benefits from Conformal Coating - Eaton Use - Variation & limitations - Relevant standards & Conclusions			X	X	X	X	
AP040183EN	Low Temperature Applications - Basics - Applications - Self-heat function - Drive configuration - Typical application			X	X	X		
AP040189EN	DX-COM-STICK3_Connection - Connect to a PC - Connect with drivesConnect mobile app - Offline parameter copy - Boot-Sequence and Unlocking			X	X	X	X	
AP040190EN	Update DX-COM-STICK3 - Connect to a PC - Enter Firmware Update Mode - Update			X	X	X	X	

6 DE1

No	Title / Content	General	900X	DA1	DC1	DC1...E1	DE1	DG1
AP040016EN	How does the internal motor protection work? • how the motor protection works • Dependency between current and tripping time • Determination of the recovery time after an overload			X	X	X	X	
AP040017EN	Motor data – Motor Protection – V/f curves – Slip Compensation • Adaptation to the connected motor • Slip compensation • Motor protection • Setting the V/f curve • Energy optimization						X	
AP040020EN	Access to Parameter Level 2 – Parameter Lock – Load Default • Access to parameter level 2 • how to prevent a parameter value change • how to restore the factory settings (Default)						X	
AP040022EN	The OP System Bus – Parameterizing – Control • Structure of the hardware • Bus configuration • Handling at parameterization and control			X	X	X	X	
AP040029EN	Starting, Stopping and Operation • different possibilities at starting and stopping • respective control commands • setting of the relevant parameters • behaviour in case of fault • measures to prevent unintended trips						X	
AP040033EN	Quick-Start-Guide DE11 • Brief description • Parameter List						X	
AP040036EN	I/O Configuration • Input and output terminals • Technical data • Assignment of functions to terminals • Configuration of the I/Os						X	

No	Title / Content	General	9000X	DA1	DC1	DC1...E1	DE1	DG1
AP040042EN	Set Point Setting - Different ways of set point setting - Handling of the references						X	
AP040092EN	Quick-Start-Guide DE1 - Brief description - Parameter List						X	
AP040181EN	Fire Mode - Configuration - How does DE1 work in Fire Mode?						X	
AP040182EN	Conformal Coating - Benefits from Conformal Coating - Eaton Use - Variation & limitations - Relevant standards & Conclusions			X	X	X	X	
AP040189EN	DX-COM-STICK3_Connection - Connect to a PC - Connect with drivesConnect mobile app - Offline parameter copy - Boot-Sequence and Unlocking			X	X	X	X	
AP040190EN	Update DX-COM-STICK3 - Connect to a PC - Enter Firmware Update Mode - Update			X	X	X	X	

7 DG1

No	Title / Content	General	900X	DA1	DC1	DC1...E1	DE1	DG1
AP040058EN	Operating at low temperatures - Configuration of the protective function "Unit Under Temp" - Cold Weather Mode							X
AP040065EN	Smoke Mode and Fire Mode - How does it work? - Configuration for Smoke Mode - Configuration for Fire Mode							X
AP040128EN	DG1 in pump and fan applications - Selection of the operation mode - Application specific functions - Multi motor systems							X
AP040129EN	Analog I/Os - Connection of the analog signals - Extension of the number of I/Os - Technical data - Assignment of terminals to functions - Configuration of the analog I/Os							X
AP040132EN	Digital I/Os - Connection of the signals - Extension of the number of I/Os - Technical data - Assignment of terminals and functions - Configuration of the digital I/Os							X
AP040164EN	PID Controller - Function of the specific parameters - Operation method of the controllers - Application examples							X
AP040168EN	Load balancing in multi motor applications Comparison and description of different possibilities to balance the load.							X
AP040172EN	Real Time Clock and Use of the Timers - Handling of the battery - Setting the real time clock - Parameterization of time based actions							X

No	Title / Content	General	9000X	DA1	DC1	DC1...E1	DE1	DG1
AP040176EN	Starting, Stopping and Operation • Configuration of the protective functions • Speed limits and setpoint setting • Ramps • Control signals • Operating modes Local and Remote • Monitor parameters • Fault management, causes, remedy • Starting and stopping							X
AP040177EN	Motor data and V/f curves • Selection of the motor control mode • Adaptation to the connected motor • Slip compensation • Setting the V/f curve							X
AP040167EN	DG1 Torque Control • Motor Control Mode • Torque references • Torque limitation • Torque threshold signalling							X

8 Rapid Link

No.	Title / Content	General	RAMO	RASP				
AP040080EN	New generation of Rapid Link units RA-SP - Aspects when changing from RA-SP2 and RA-SPV to RASP - Dimensions - ASi Profile - Parameter software and technical overview - Type and design of motor cables			X				
AP040081EN	New generation of Rapid Link units RA-MO - Aspects when changing from RA-MO-RA.. and RA-MO-W..to RAMO - Dimensions - ASi Profile - Parameter software and technical overview - Type and design of motor cables		X					
AP040197EN	Generation Change RASP4 to RASP5 - AS-I Profile - Dimensions - Connections - Parameter & Software			X				
AP040198EN	Generation change RAMO4 to RAMO5 - AS-I Profile - Dimensions - Connections - Parameter & Software		X					
AP040195EN	Configuration to Rockwell PLC for Rapid Link - System overview - Material for the Application - Connections		X	X				
New AP040196EN	Generation Change RA-SP to RASP5 - Aspects when changing from RA-SP to RASP5 - AS-I Profile - Dimensions - Connections - Parameter & Software			X				

9 Softstarter

Nr.	Title / Content	General	DS7	S8x1+				
AP039013EN	Switching from S801+ to S811+ • Paramerization via keypad • Parameter settings DIP switch vs. keypad • Change of the devices • Connection DIP switch on keypad • Parameter setup (Operation & Protection Mode) • S811+ parameter			X				

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